

Characterizing Implementability of Global Protocols with Infinite States and Data

Elaine Li



Felix Stutz



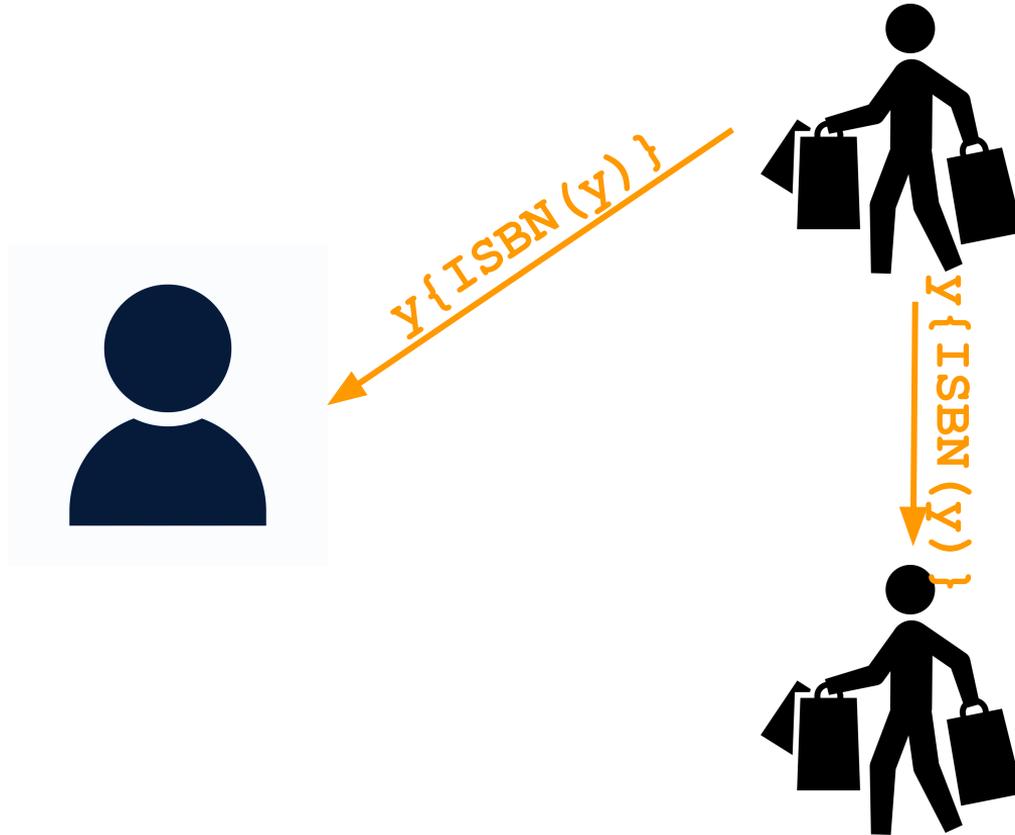
Thomas Wies



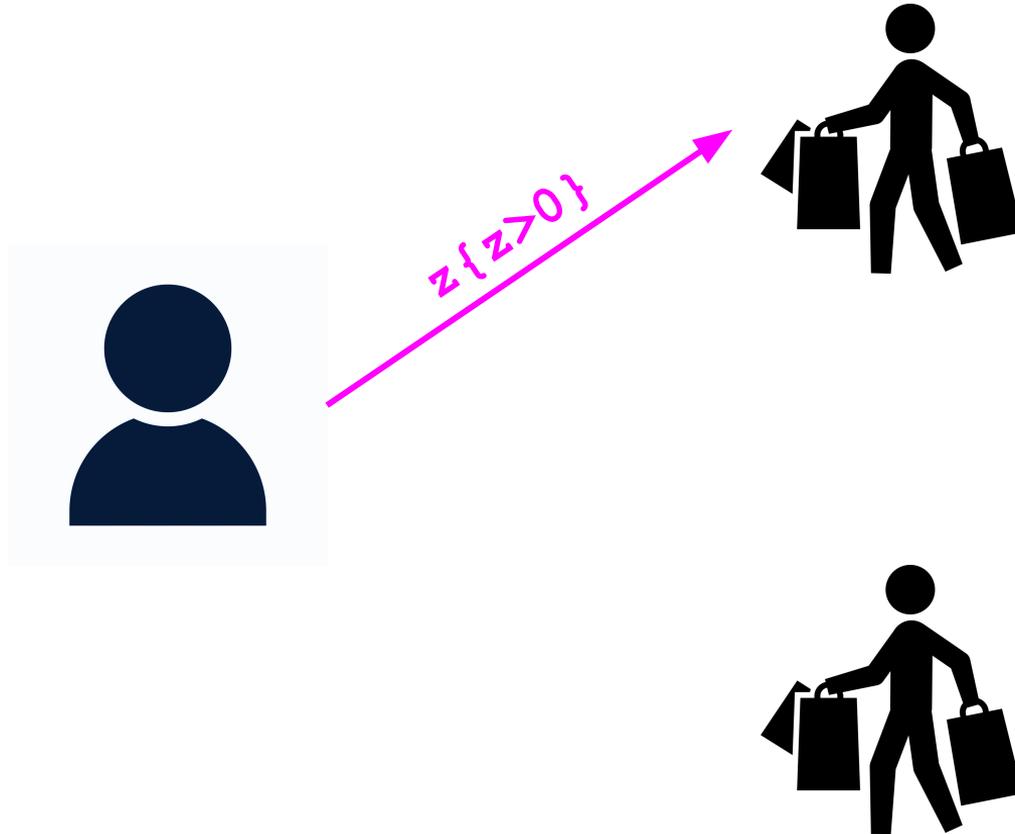
Damien Zufferey



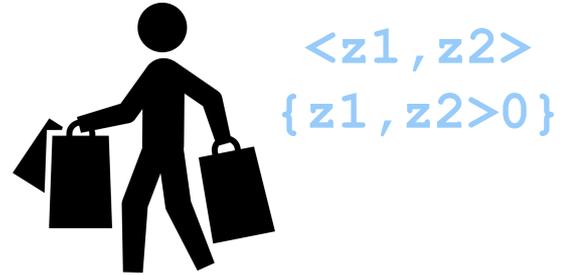
Global protocols: two-bidder protocol



Global protocols: two-bidder protocol



Global protocols: two-bidder protocol

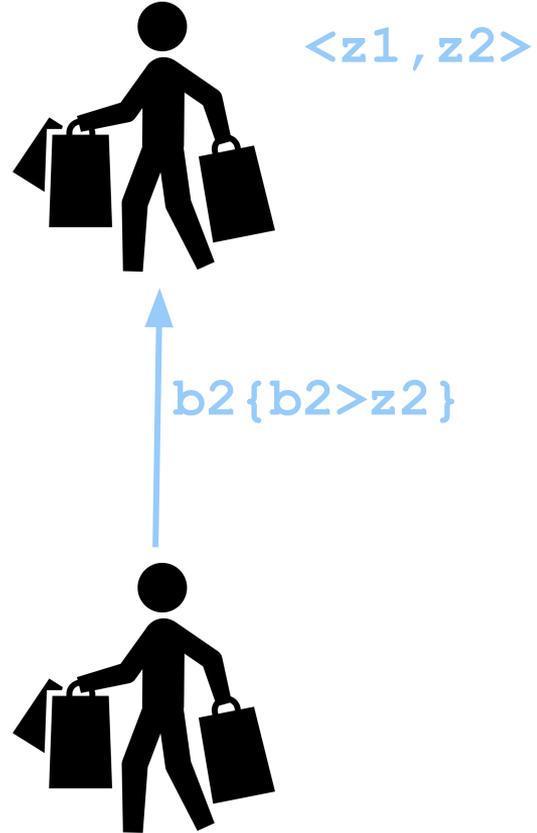


$\langle z_1, z_2 \rangle$
 $\{z_1, z_2 > 0\}$

$b_1 \{b_1 > z_1\}$



Global protocols: two-bidder protocol



Global protocols: two-bidder protocol

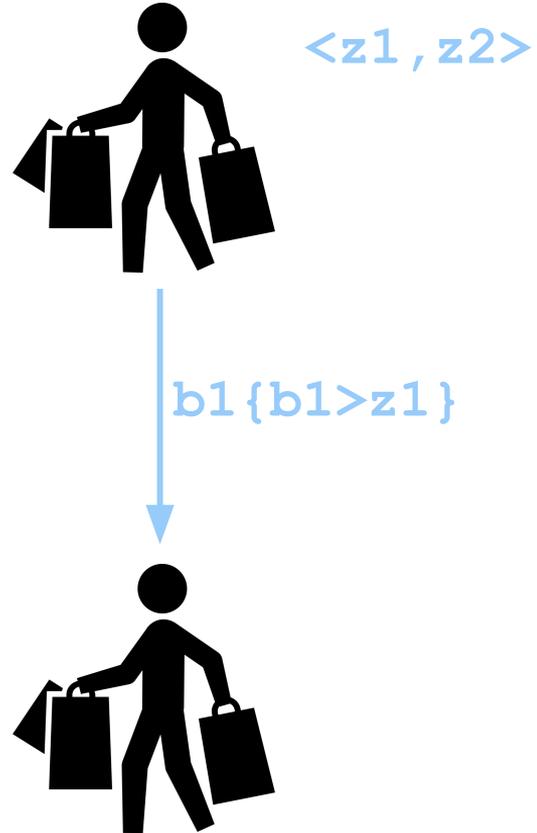


$\langle z1 := b1, z2 := b2 \rangle$

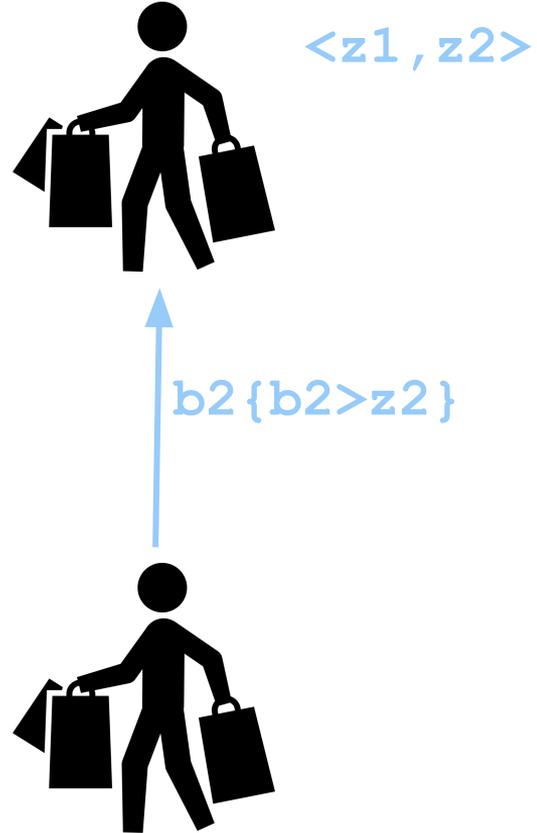
$\text{cont}\{b1+b2 < z\}$



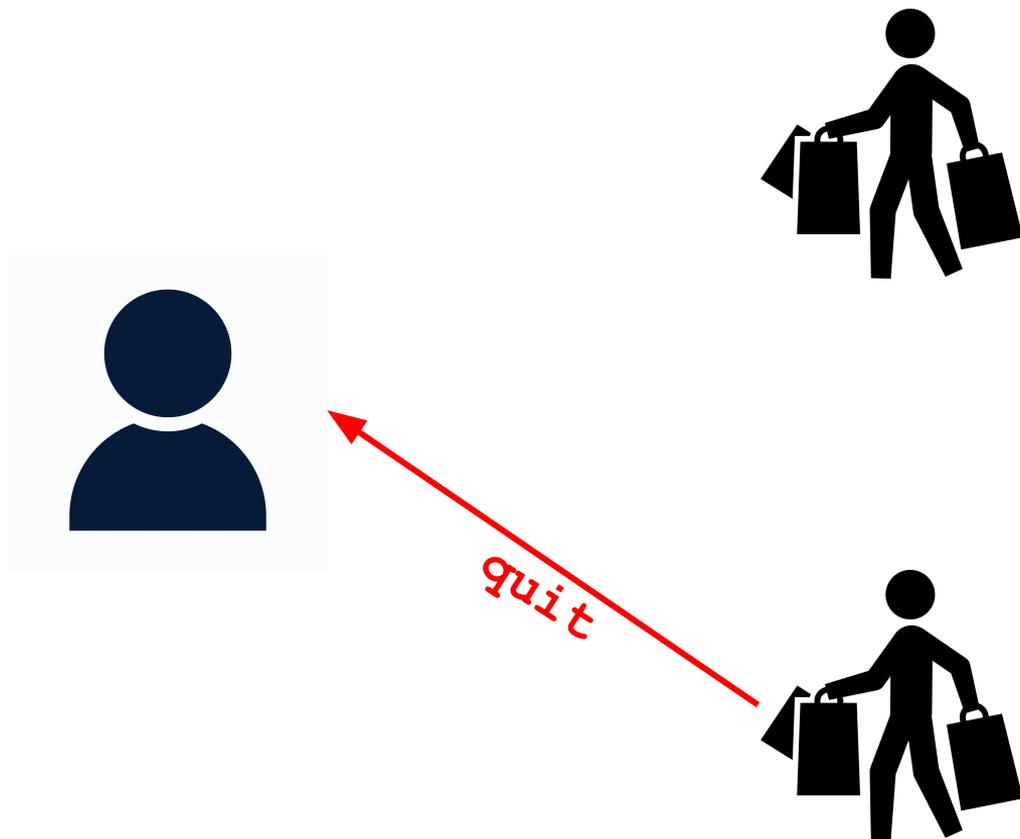
Global protocols: two-bidder protocol



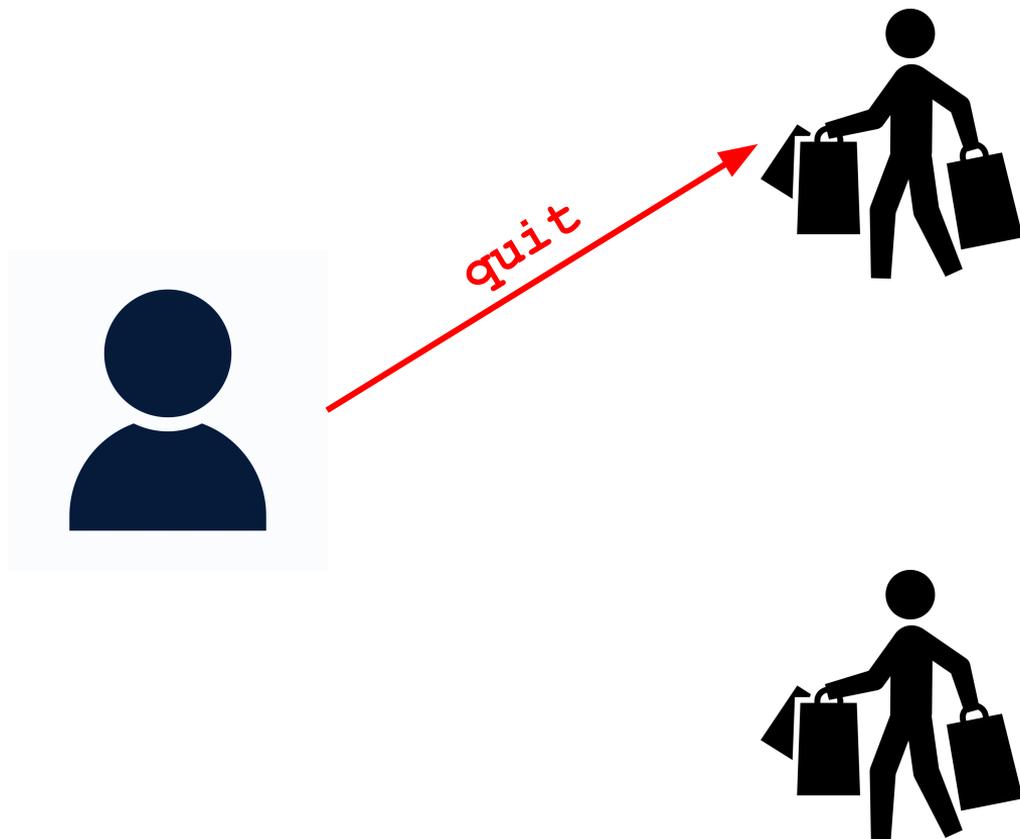
Global protocols: two-bidder protocol



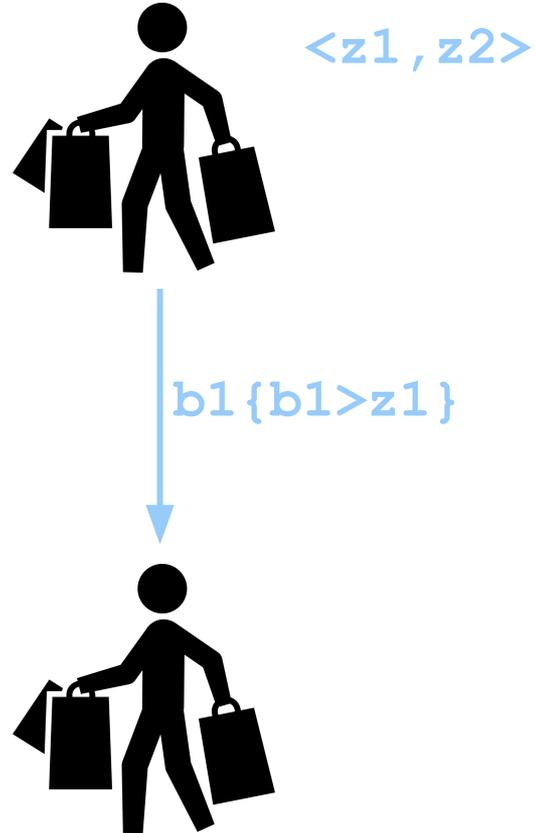
Global protocols: two-bidder protocol



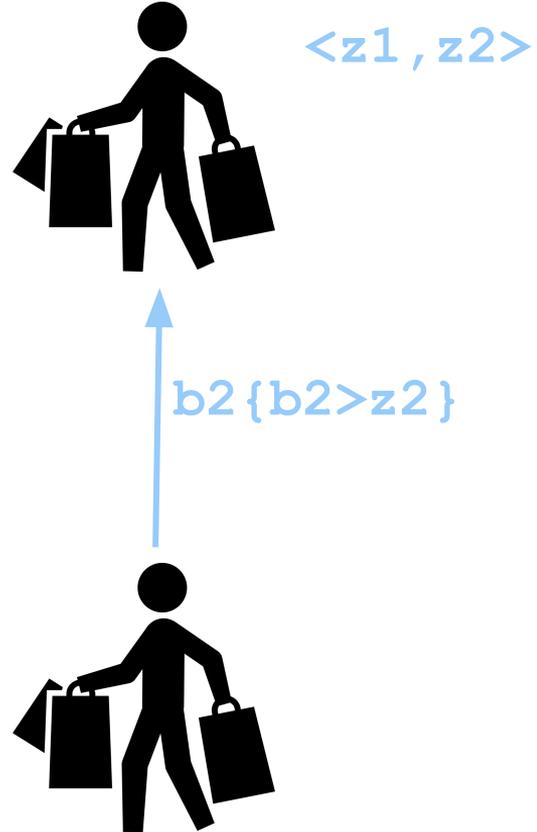
Global protocols: two-bidder protocol



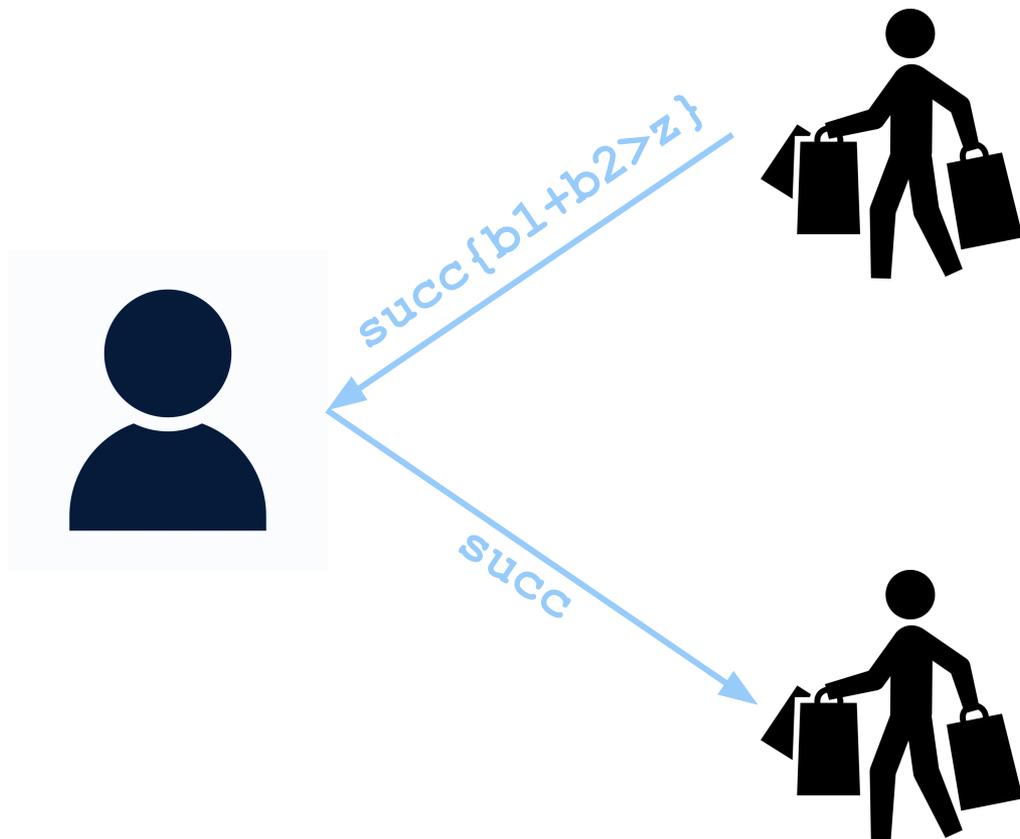
Global protocols: two-bidder protocol



Global protocols: two-bidder protocol



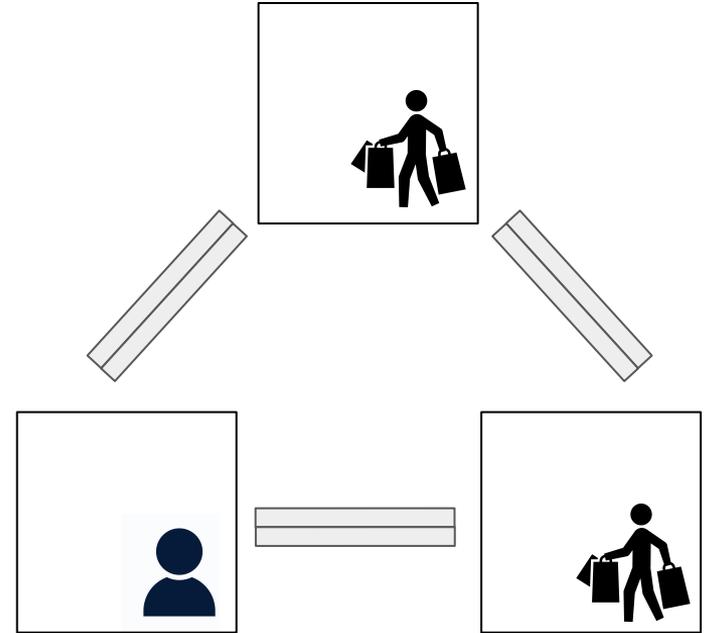
Global protocols: two-bidder protocol



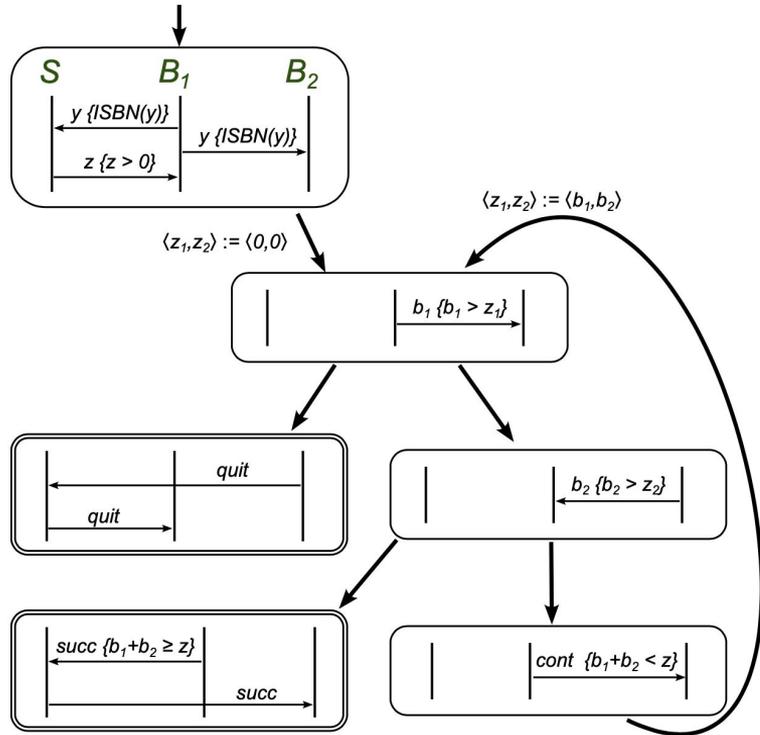
Overview

Asynchronous, message-passing programs are challenging to implement individually

- Communication errors e.g. orphan messages, unspecified receptions
- Deadlocks



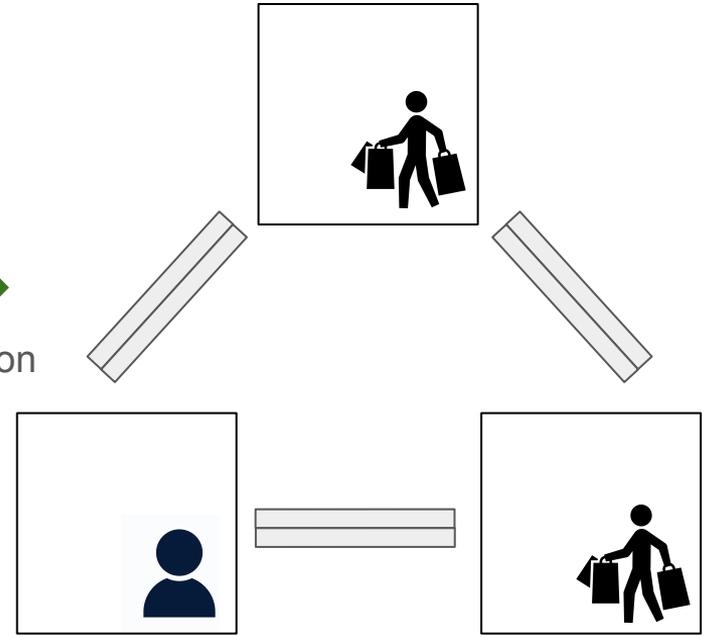
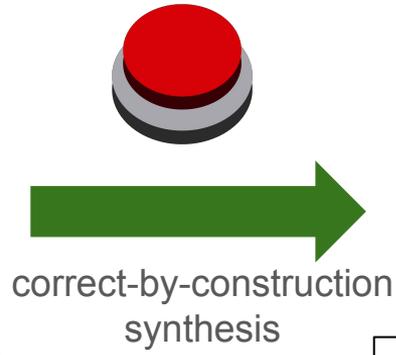
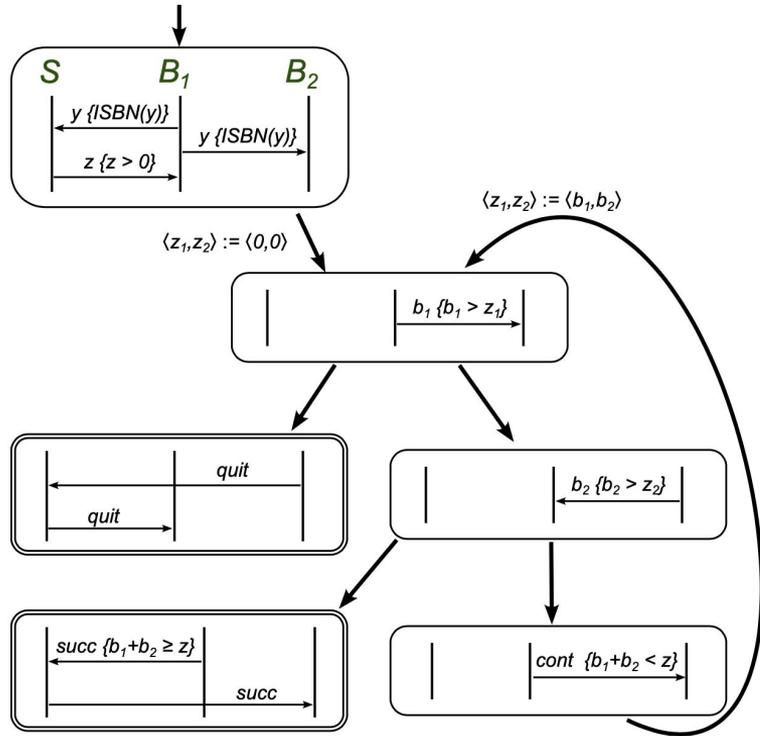
Overview



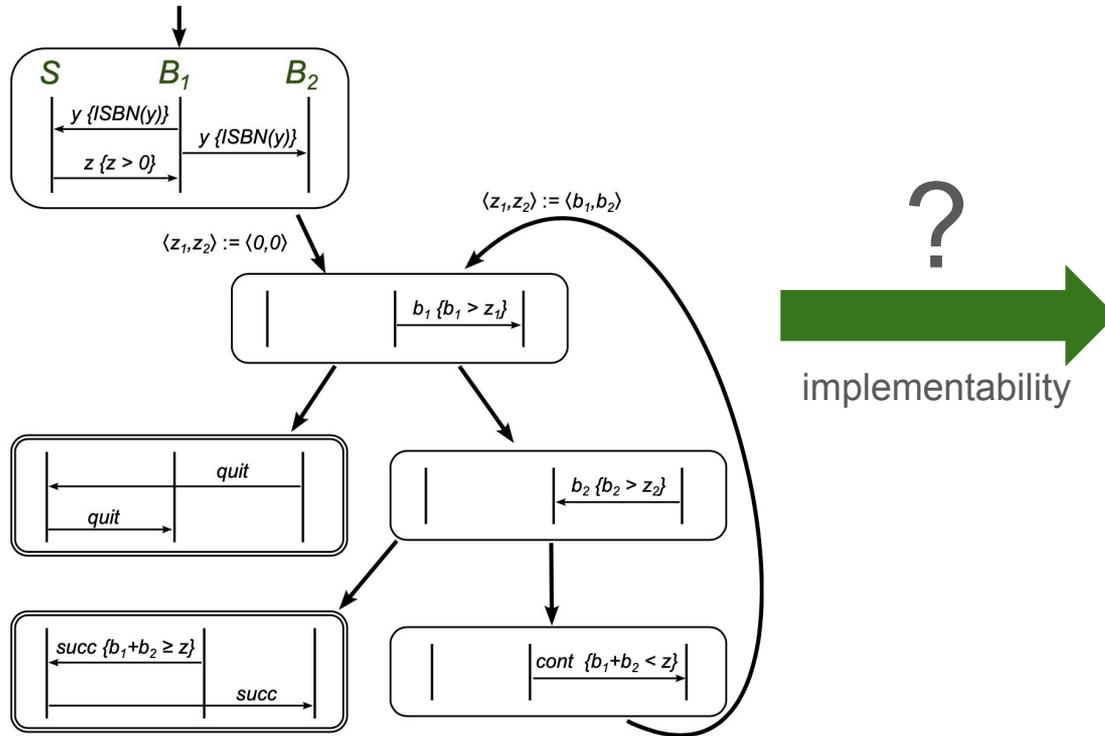
Global protocols are **synchronous** specifications of **all** participants' behaviors

- High-level message sequence charts [Mauw and Reniers 97]
- Session types [Honda et al. 08]
- Choreographic programming [Carbone and Montesi 13]

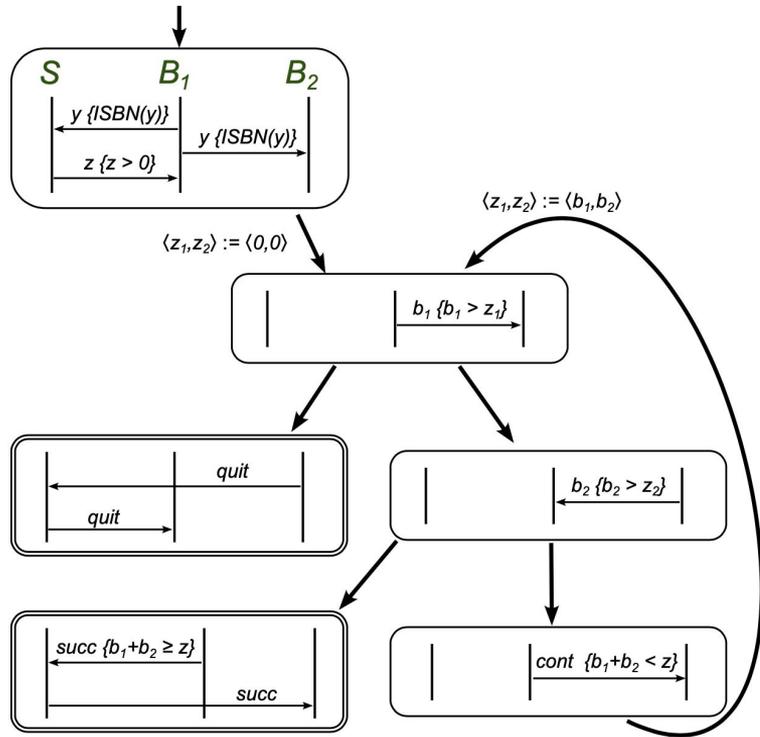
Overview



Overview



Overview



?

→

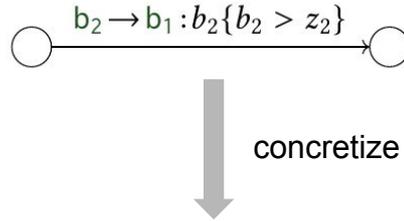
implementability

\approx

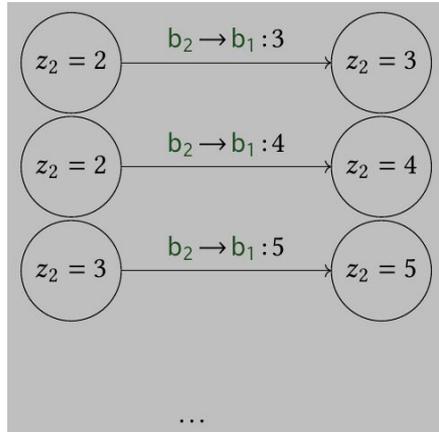
$L_1 = L_2?$

Global protocol semantics

Symbolic transition

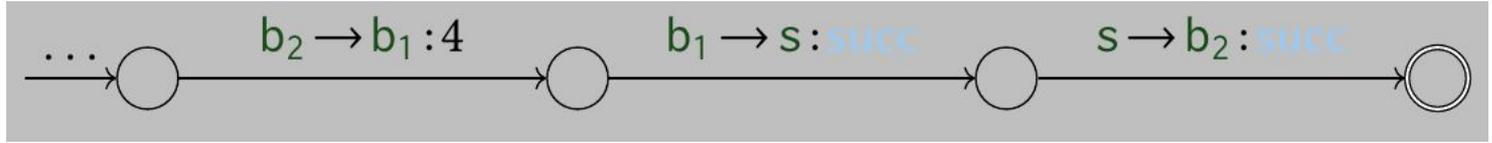


Concrete transition



Global protocol semantics

Concrete run



Synchronous

... $b_2 \rightarrow b_1:4 \cdot b_1 \rightarrow s:succ \cdot s \rightarrow b_2:succ$



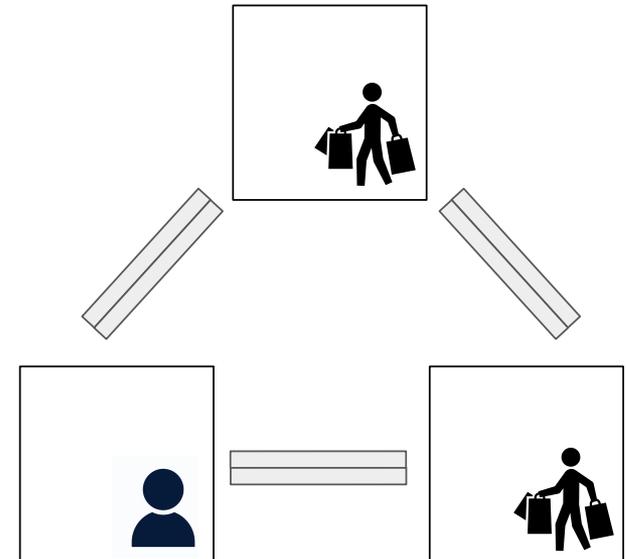
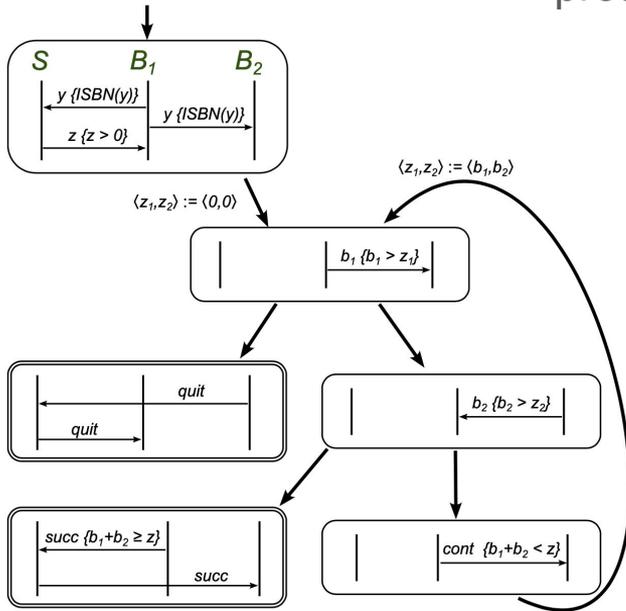
Asynchronous

... $b_2! b_1:4 \cdot b_1? b_2:4 \cdot b_2! s:succ \cdot s? b_2:succ \cdot s! b_2:succ \cdot b_2? s:succ$

...closed under CLTS-equivalence

Implementability

Implementability = exists a CLTS satisfying
protocol fidelity + deadlock freedom?

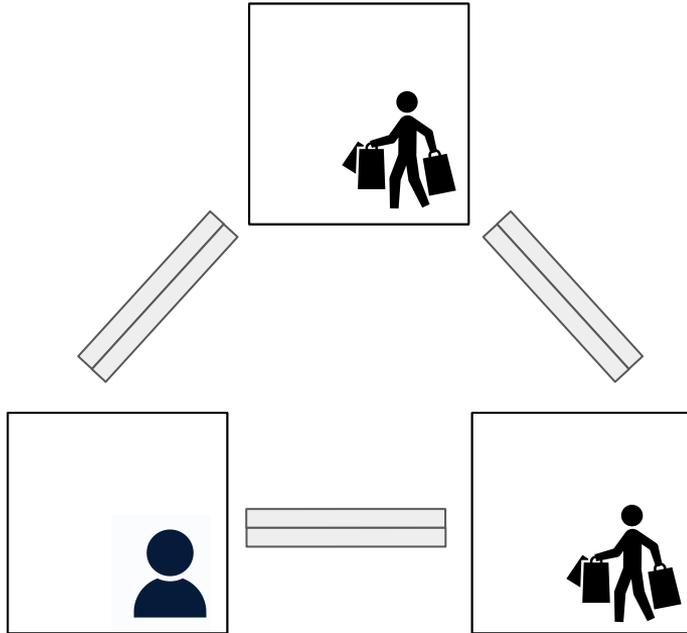


Implementation model

(controllable)

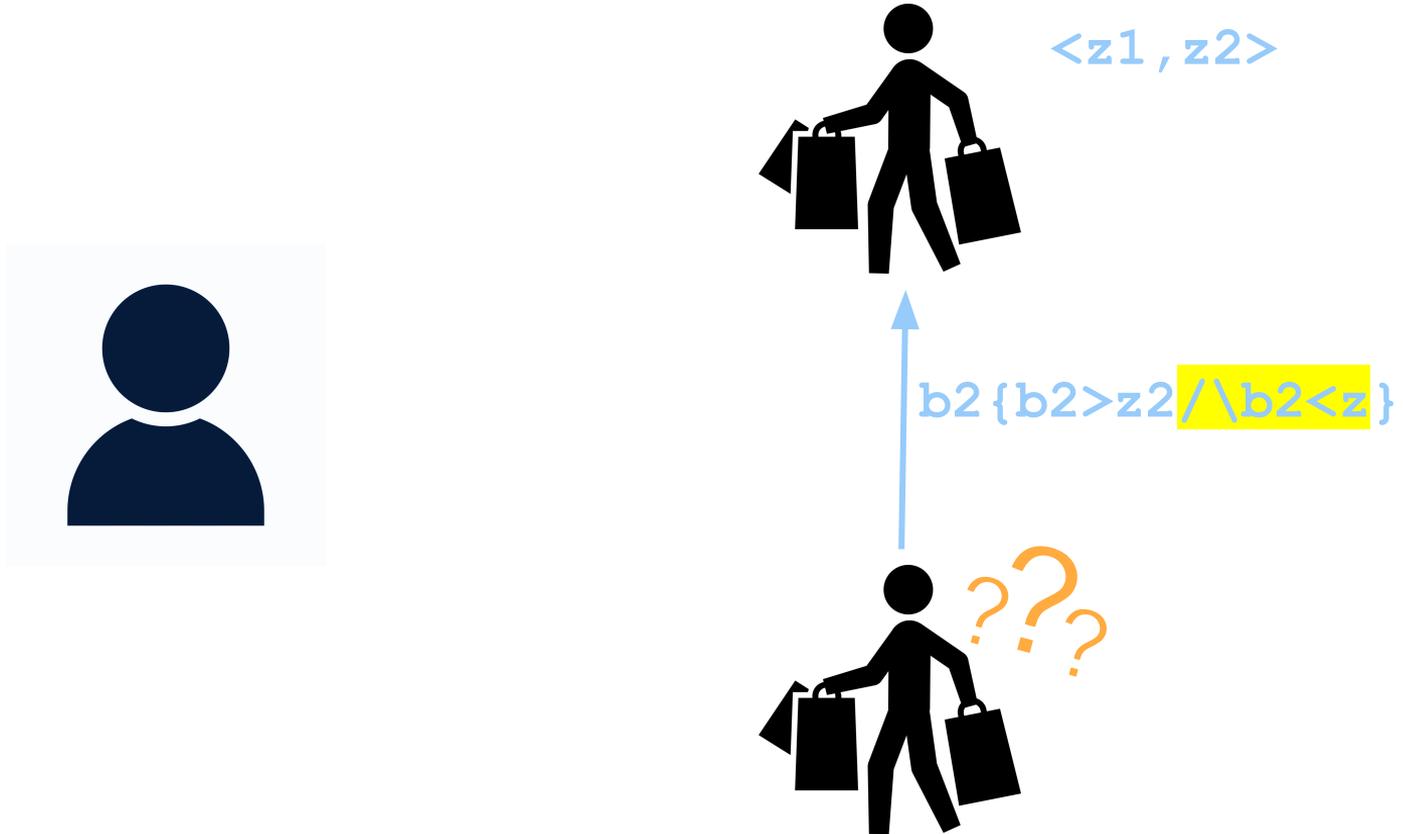
(non-controllable)

Communicating Labeled Transition System (CLTS) = per participant LTS + peer-to-peer FIFO channels

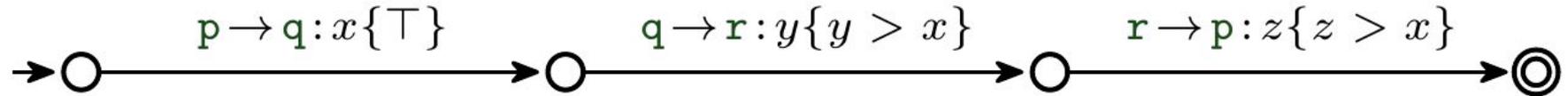


- Infinite-state generalization of CSMs [Brand and Zafiropulo 83]
- Message delay, reordering, ~~dropping, duplication~~

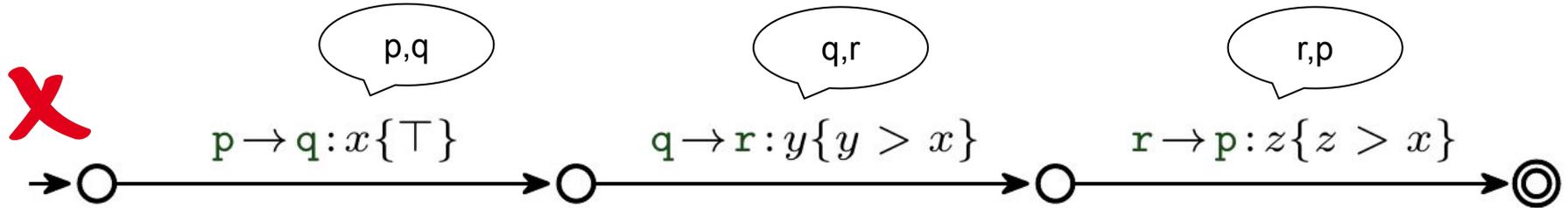
Non-implementability: two-bidder protocol



Non-implementability

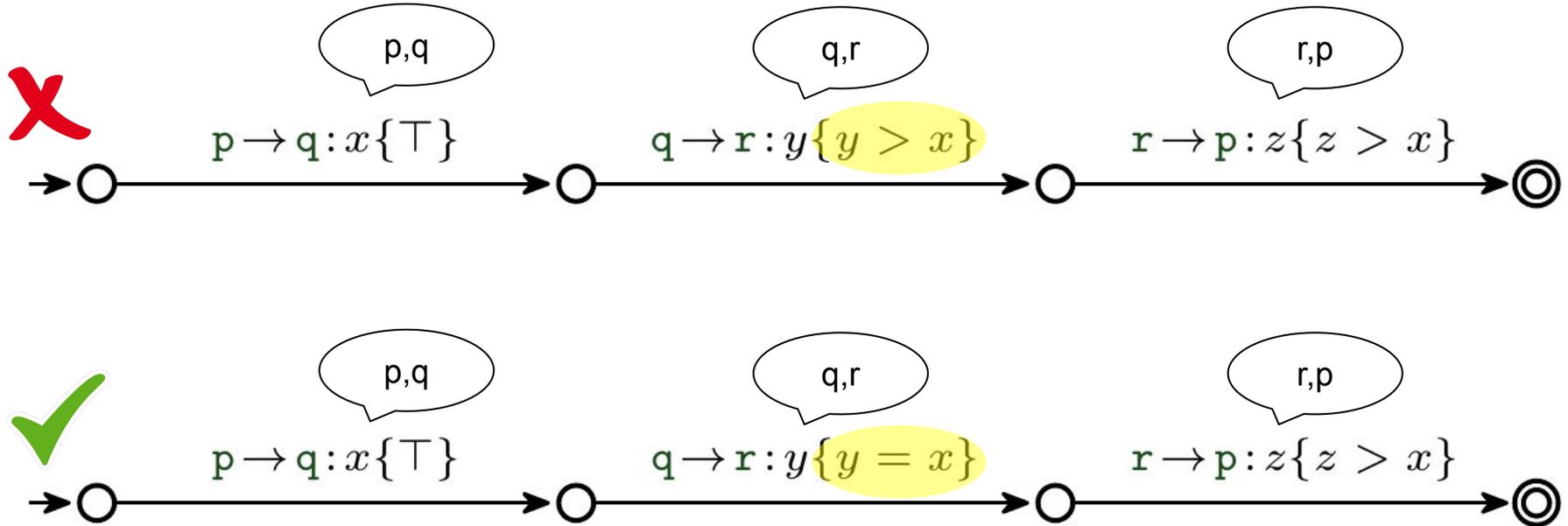


Non-implementability

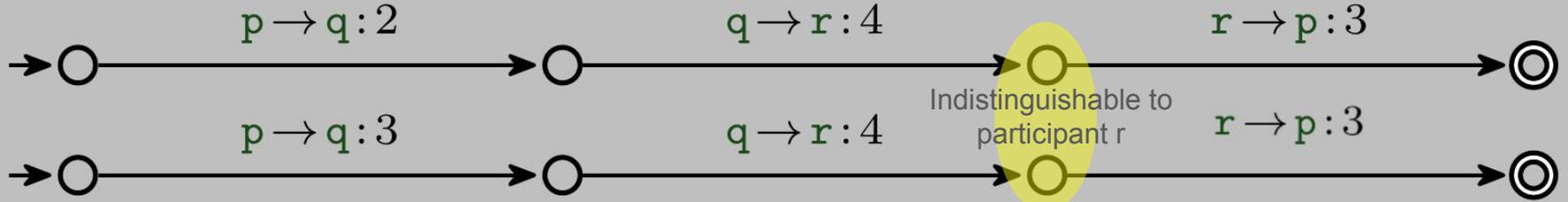
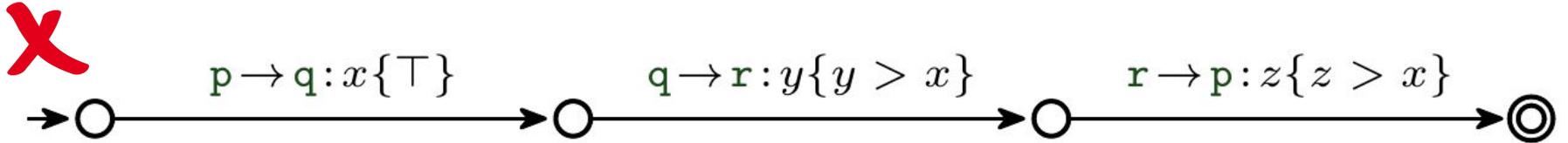


Syntactic classification of "known" and "unknown" variables [Zhou et al. 20]

Non-implementability



Non-implementability



Coherence Conditions



From two locally indistinguishable global states, a participant can either:

- Send a message permissible from both states (Send Coherence)
- Receive a message that distinguishes the two states (Receive Coherence)

but cannot choose between sending or receiving a message (No Mixed Choice)

Coherence Conditions



From two locally indistinguishable global states, a participant can either:

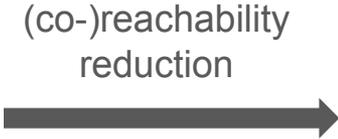
- Send a message permissible from both states (Send Coherence)
- Receive a message that distinguishes the two states (Receive Coherence)

but cannot choose between sending or receiving a message (No Mixed Choice)

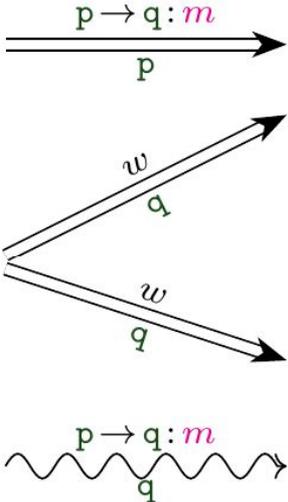
Theorem. A concrete protocol* is implementable if and only if it satisfies the Coherence Conditions.

Deciding implementability, part one

Implementability



Coherence Conditions



Algorithm for finite protocols

Algorithm 1 Check CC for finite protocols

▸ Let LTS $\mathcal{S} = (S, \Gamma, T, s_0, F)$

▸ *Checking Send Coherence*

for $s_1 \xrightarrow{p \rightarrow q:m} s_2 \in T$ **do**

for $s \neq s_1 \in S$ **do**

if $\mathcal{L}(S, \Gamma_p \uplus \{\varepsilon\}, T_p, s_0, \{s\}) \cap \mathcal{L}(S, \Gamma_p \uplus \{\varepsilon\}, T_p, s_0, \{s_1\}) \neq \emptyset$ **then**

$b \leftarrow \perp$

for $s_3 \xrightarrow{p \rightarrow q:m} s_4 \in T$ **do** $b \leftarrow b \vee \left(s \xrightarrow[p]{\varepsilon}^* s_3 \right)$

if $\neg b$ **then return** \perp

▸ *Checking Receive Coherence*

for $s_1 \xrightarrow{p \rightarrow q:m} s_2, s_3 \xrightarrow{r \rightarrow q:m} s_4 \in T, s_1 \neq s_2, p \neq r$ **do**

if $\mathcal{L}(S, \Gamma_q \uplus \{\varepsilon\}, T_q, s_0, \{s_1\}) \cap \mathcal{L}(S, \Gamma_q \uplus \{\varepsilon\}, T_q, s_0, \{s_3\}) \neq \emptyset$ **then**

if $\text{avail}_{p,q,\{q\}}(m, s_4)$ **then return** \perp

▸ *Checking No Mixed Choice*

for $s_1 \xrightarrow{p \rightarrow q:m} s_2, s_3 \xrightarrow{r \rightarrow p:m} s_4 \in T, s_1 \neq s_2$ **do**

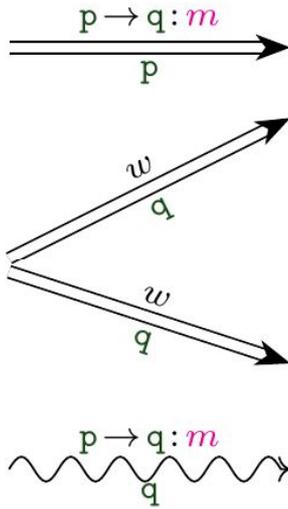
if $\mathcal{L}(S, \Gamma_q \uplus \{\varepsilon\}, T_q, s_0, \{s_1\}) \cap \mathcal{L}(S, \Gamma_q \uplus \{\varepsilon\}, T_q, s_0, \{s_3\}) \neq \emptyset$ **then return** \perp

return \top

Deciding implementability, part two

Symbolic Coherence Conditions

Coherence Conditions



μ CLP
reduction
(first-order fixpoint logic modulo theories)

$$\text{unreach}_{p,q}^{\epsilon}(s, r, x) := \nu$$

$$\wedge \left(\bigwedge_{(s, p \rightarrow q : y \{ \varphi \}, s') \in \Delta} \neg \varphi[x/y] \right)$$

$$\wedge \left(\bigwedge_{\substack{(s, q \rightarrow t : y \{ \varphi \}, s') \in \Delta \\ p \neq q \wedge p \neq t}} \forall y. \varphi \Rightarrow \text{unreach}_{p,q}^{\epsilon}(s', r', x) \right)$$

$$\text{avail}_{p,q,B}(x_1, s, r) := \mu$$

$$\bigvee_{\substack{(s, r \rightarrow t : x \{ \varphi \}, s') \in \Delta \\ r \in B \\ r \neq p \vee t \neq q}} \exists x. \text{avail}_{p,q,B \cup \{t\}}(x_1, s', r') \wedge \varphi$$

$$\bigvee_{\substack{(s, r \rightarrow t : x \{ \varphi \}, s') \in \Delta \\ r \in B \\ r \neq p \vee t \neq q}} \exists x. \text{avail}_{p,q,B}(x_1, s', r') \wedge \varphi$$

$$\bigvee_{(s, p \rightarrow q : x \{ \varphi \}, s') \in \Delta, p \notin B} \varphi[x_1/x]$$

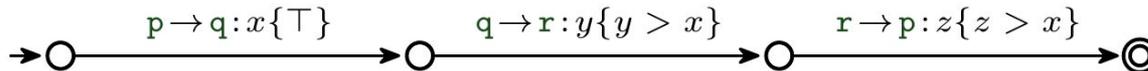
$$\text{prodreach}_p(s'_1, r'_1, s'_2, r'_2) := \mu$$

$$\vee (s'_1 = s_0 \wedge s'_2 = s_0)$$

$$\vee \left(\bigvee_{\substack{(s_1, r \rightarrow s : x_1 \{ \varphi_1 \}, s'_1) \in \Delta_1 \\ (s_2, r \rightarrow s : x_2 \{ \varphi_2 \}, s'_2) \in \Delta_2 \\ p = r \vee p = s}} \exists x_1 x_2. \text{prodreach}_p(s_1, r_1, s_2, r_2) \wedge \varphi_1 \wedge \varphi_2 \wedge x_1 = x_2 \right)$$

$$\vee \left(\bigvee_{\substack{(s_1, r \rightarrow s : x_1 \{ \varphi_1 \}, s'_1) \in \Delta_1 \\ p \neq r \wedge p \neq s}} \exists x_1. \text{prodreach}_p(s_1, r_1, s'_2, r'_2) \wedge \varphi_1 \right)$$

$$\vee \left(\bigvee_{\substack{(s_2, r \rightarrow s : x_2 \{ \varphi_2 \}, s'_2) \in \Delta_2 \\ p \neq r \wedge p \neq s}} \exists x_2. \text{prodreach}_p(s'_1, r'_1, s_2, r_2) \wedge \varphi_2 \right)$$



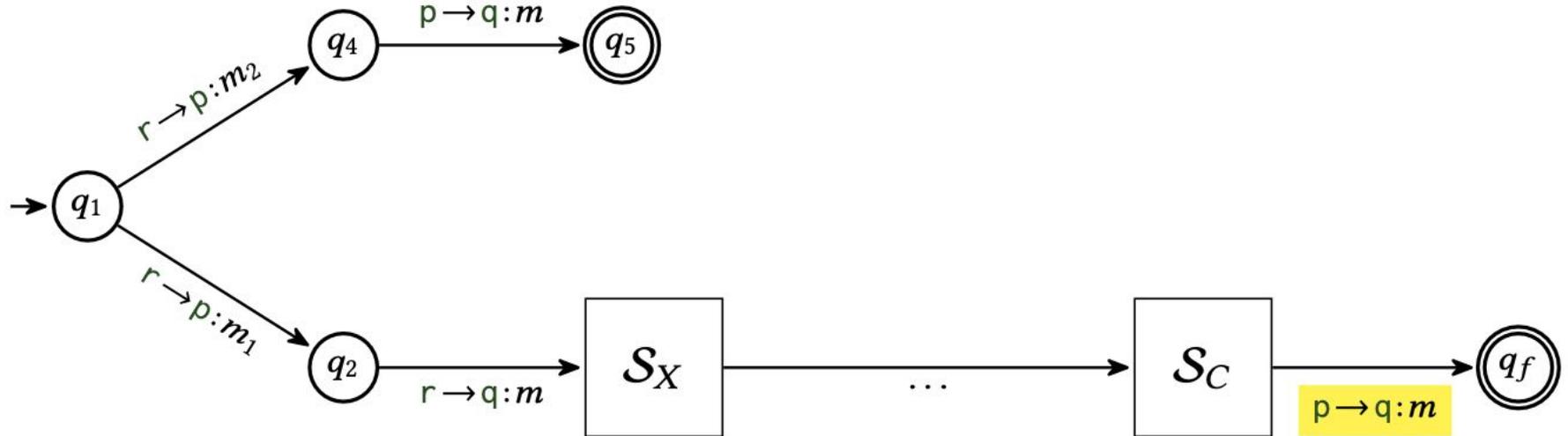
Complexity

Fragment	Complexity
Symbolic, boolean	PSPACE-complete
Non-symbolic	co-NP-complete
Multiparty session types	co-NP-complete

Complexity

3-SAT instance: set of variables X , set of clauses C

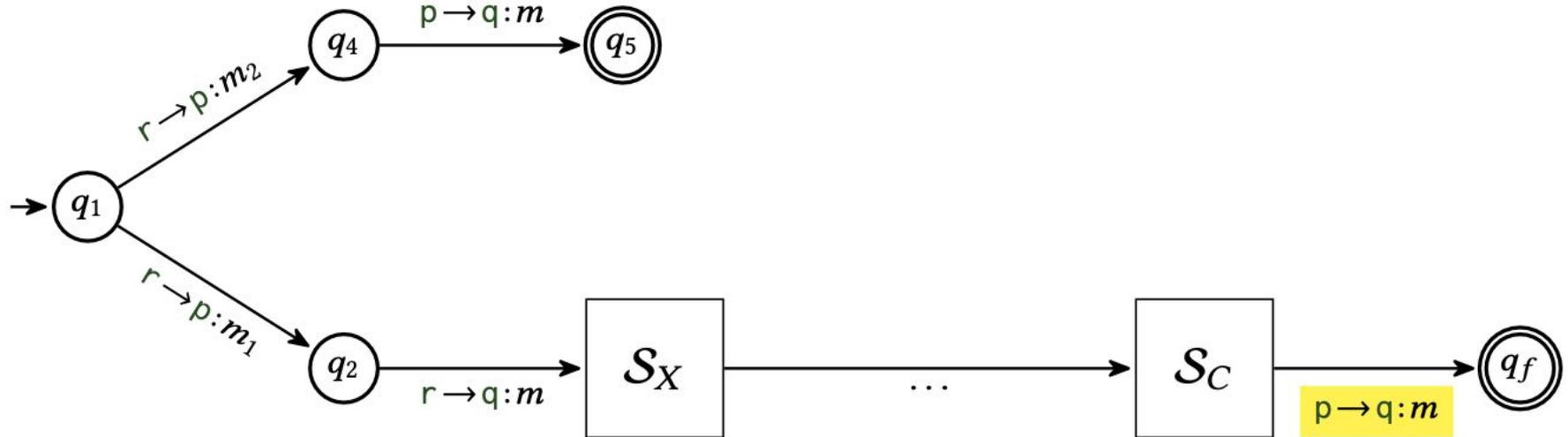
S is implementable iff 3-SAT instance is satisfiable



Complexity

3-SAT instance: set of variables X , set of clauses C

~~S is implementable~~ m is *receivable* iff 3-SAT instance is satisfiable



Synthesis

Theorem. If a concrete protocol is implementable, then the *canonical* implementation implements it.

- Synthesis is as hard as determinizing the specification fragment
- Off-the-shelf determinization algorithms:
 - All finite fragments (subset construction)
 - Symbolic finite automata (modified subset construction)
 - Classes of timed and register automata

Conclusion

- First sound and (relatively) complete algorithm for deciding implementability of symbolic global protocols
- Improves prior work in terms of **expressivity**, **completeness** and **complexity**



- Extras: Sprout implementation [Li et al. CAV'25], Rocq mechanization [Li and Wies ITP'25]

Conclusion

- First sound and (relatively) complete algorithm for deciding implementability of symbolic global protocols
- Improves prior work in terms of **expressivity**, **completeness** and **complexity**



- Extras: Sprout implementation [Li et al. CAV'25], Rocq mechanization [Li and Wies ITP'25]

Thank you!